# FLUXBRANE AND $S$-BRANE SOLUTIONS RELATED TO LIE ALGEBRAS 

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We overview composite fluxbrane and special $S$-brane solutions for a wide class of intersection rules related to semisimple Lie algebras. These solutions are defined on a product manifold $R_{*} \times$ $M_{1} \times \ldots \times M_{n}$ which contains $n$ Ricci-flat spaces $M_{1}, \ldots, M_{n}$ with one-dimensional $R_{*}$ and $M_{1}$. They are governed by a set of moduli functions $H_{s}$, which have polynomial structure. The powers of polynomials coincide with the components of the dual Weyl vector in the basis of simple coroots.

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## INTRODUCTION

In this paper we overview fluxbrane and special $S$-brane solutions related to semisimple finite-dimensional (FD) Lie algebras [1,2]. These solutions contain a subclass of (partially) supersymmetric solutions related to Lie algebras $A_{1} \oplus \ldots \oplus$ $A_{1}$ (at least for $M_{i}=\mathbf{R}^{d_{i}}$ ). The solutions are governed by functions $H_{s}(z)>0$ defined on the interval $(0,+\infty)$ and obeying differential equations

$$
\begin{equation*}
\frac{d}{d z}\left(\frac{z}{H_{s}} \frac{d}{d z} H_{s}\right)=\frac{1}{4} B_{s} \prod_{s^{\prime} \in S} H_{s^{\prime}}^{-A_{s s^{\prime}}} \tag{1}
\end{equation*}
$$

with the boundary conditions imposed:

$$
\begin{equation*}
H_{s}(+0)=1 \tag{2}
\end{equation*}
$$

$s \in S$ ( $S$ is nonempty set). Here and in what follows all $B_{s}>0$ are constants, and $\left(A_{s s^{\prime}}\right)$ is the Cartan matrix $\left(A_{s s}=2\right)$ of some semisimple FD Lie algebra $\mathcal{G}$.

[^0]It was conjectured in [1] that Eqs.(1),(2) have polynomial solutions. For semisimple Lie algebra the powers of polynomials coincide with the components of the dual Weyl vector in the basis of simple coroots. In [1,2] the polynomials corresponding to Lie algebras $A_{1} \oplus \ldots \oplus A_{1}, A_{2}, C_{2}$, and $G_{2}$ were presented. The conjecture may be verified for any classical simple Lie algebra using the program from [3], where the polynomials corresponding to exceptional Lie algebras $F_{4}$ and $E_{6}$ were found as well.

## 1. «FLUX-S-BRANE» SOLUTIONS

We consider a model governed by the action

$$
\begin{equation*}
S=\int d^{D} x \sqrt{|g|}\left\{R[g]-h_{\alpha \beta} g^{M N} \partial_{M} \varphi^{\alpha} \partial_{N} \varphi^{\beta}-\sum_{a \in \Delta} \frac{\theta_{a}}{N_{a}!} \exp \left[2 \lambda_{a}(\varphi)\right]\left(F^{a}\right)^{2}\right\} \tag{3}
\end{equation*}
$$

where $g=g_{M N}(x) d x^{M} \otimes d x^{N}$ is a metric, $\varphi=\left(\varphi^{\alpha}\right) \in \mathbf{R}^{l}$ is a vector of scalar fields, $\left(h_{\alpha \beta}\right)$ is a constant symmetric nondegenerate $l \times l \operatorname{matrix}(l \in \mathbf{N}), \theta_{a}= \pm 1$, $F^{a}=d A^{a}$ is a $N_{a}$-form $\left(n_{a} \geqslant 1\right), \lambda_{a}$ is a 1-form on $\mathbf{R}^{l}: \lambda_{a}(\varphi)=\lambda_{a \alpha} \varphi^{\alpha}, a \in \triangle$, $\alpha=1, \ldots, l$. Here $\Delta$ is some finite set.

Let us consider a family of exact solutions to field equations corresponding to the action (3) and depending on one variable $\rho$. These solutions are defined on the manifold

$$
\begin{equation*}
M=(0,+\infty) \times M_{1} \times M_{2} \times \ldots \times M_{n} \tag{4}
\end{equation*}
$$

where $M_{1}$ is one-dimensional manifold. The solutions read [2]

$$
\begin{align*}
& g=\left(\prod_{s \in S} H_{s}^{2 h_{s} d\left(I_{s}\right) /(D-2)}\right)\{w d \rho \otimes d \rho+\left(\prod_{s \in S} H_{s}^{-2 h_{s}}\right) \rho^{2} g^{1}+ \\
&\left.+\sum_{i=2}^{n}\left(\prod_{s \in S} H_{s}^{-2 h_{s} \delta_{i I_{s}}}\right) g^{i}\right\}  \tag{5}\\
& \exp \left(\varphi^{\alpha}\right)=\prod_{s \in S} H_{s}^{h_{s} \chi_{s} \lambda_{a_{s}}^{\alpha}}  \tag{6}\\
& F^{a}=\sum_{s \in S_{e}}\left(-Q_{s}\right)\left(\prod_{s^{\prime} \in S} H_{s^{\prime}}^{-A_{s s^{\prime}}}\right) \rho d \rho \wedge \tau\left(I_{s}\right)+\sum_{s \in S_{m}} Q_{s} \tau\left(\bar{I}_{s}\right) \tag{7}
\end{align*}
$$

Functions $H_{s}(z)>0, z=\rho^{2}$ obey Eq. (1) with boundary conditions (2).

In Eq. (5), $g^{i}=g_{m_{i} n_{i}}^{i}\left(y_{i}\right) d y_{i}^{m_{i}} \otimes d y_{i}^{n_{i}}$ is a Ricci-flat metric on $M_{i}, i=$ $1, \ldots, n$,
$\delta_{i I}=\sum_{j \in I} \delta_{i j}$ is the indicator of $i$ belonging to $I: \delta_{i I}=1$ for $i \in I$ and $\delta_{i I}=0$ otherwise.

By definition the brane set $S$ is the union of two sets:

$$
\begin{equation*}
S=S_{e} \cup S_{m}, \quad S_{v}=\cup_{a \in \Delta}\{a\} \times\{v\} \times \Omega_{a, v} \tag{8}
\end{equation*}
$$

$v=e, m$ and $\Omega_{a, e}, \Omega_{a, m} \subset \Omega$, where $\Omega=\Omega(n)$ is the set of all nonempty subsets of $\{1, \ldots, n\}$. Any brane index $s \in S$ has the form $s=\left(a_{s}, v_{s}, I_{s}\right)$, where $a_{s} \in \triangle$ is color index, $v_{s}=e, m$ is electro-magnetic index and the set $I_{s} \in \Omega_{a_{s}, v_{s}}$ describes the location of brane worldvolume.

The sets $S_{e}$ and $S_{m}$ define electric and magnetic branes, correspondingly. In Eq. (6), $\chi_{s}=+1,-1$ for $s \in S_{e}, S_{m}$, respectively. In Eq. (7), $\bar{I} \equiv I_{0} \backslash I$, $I_{0}=\{1, \ldots, n\}$.

All manifolds $M_{i}$ are assumed to be oriented and connected and the volume $d_{i}$-forms $\tau_{i} \equiv \sqrt{\left|g^{i}\left(y_{i}\right)\right|} d y_{i}^{1} \wedge \ldots \wedge d y_{i}^{d_{i}}$, and parameters $\varepsilon(i) \equiv \operatorname{sign}(\operatorname{det} \times$ $\left.\times\left(g_{m_{i} n_{i}}^{i}\right)\right)= \pm 1$ are well-defined for all $i=1, \ldots, n$. Here $d_{i}=\operatorname{dim} M_{i}$, $i=1, \ldots, n, D=1+\sum_{i=1}^{n} d_{i}$. For any $I=\left\{i_{1}, \ldots, i_{k}\right\} \in \Omega, i_{1}<\ldots<i_{k}$, we denote $\tau(I) \equiv \tau_{i_{1}} \wedge \ldots \wedge \tau_{i_{k}}, d(I) \equiv \operatorname{dim} M(I)=\sum_{i \in I} d_{i}, \varepsilon(I) \equiv \varepsilon\left(i_{1}\right) \ldots \varepsilon\left(i_{k}\right)$.

The parameters $h_{s}$ appearing in the solution satisfy the relations $h_{s}=K_{s}^{-1}$, $K_{s}=B_{s s}$, where

$$
\begin{equation*}
B_{s s^{\prime}} \equiv d\left(I_{s} \cap I_{s^{\prime}}\right)+\frac{d\left(I_{s}\right) d\left(I_{s^{\prime}}\right)}{2-D}+\chi_{s} \chi_{s^{\prime}} \lambda_{a_{s} \alpha} \lambda_{a_{s^{\prime}} \beta} h^{\alpha \beta} \tag{9}
\end{equation*}
$$

$s, s^{\prime} \in S$, with $\left(h^{\alpha \beta}\right)=\left(h_{\alpha \beta}\right)^{-1}$. In Eq. (6), $\lambda_{a_{s}}^{\alpha}=h^{\alpha \beta} \lambda_{a_{s} \beta}$. Here we assume that: $(i) B_{s s} \neq 0$, for all $s \in S$, and (ii) $\operatorname{det}\left(B_{s s^{\prime}}\right) \neq 0$, i.e., the matrix $\left(B_{s s^{\prime}}\right)$ is a nondegenerate one. In Eqs. (1) and (7), we put

$$
\begin{equation*}
\left(A_{s s^{\prime}}\right)=\left(\frac{2 B_{s s^{\prime}}}{B_{s^{\prime} s^{\prime}}}\right) \tag{10}
\end{equation*}
$$

In Eq. (1), $B_{s}=\varepsilon_{s} K_{s} Q_{s}^{2}, s \in S$, where $\varepsilon_{s}=(-\varepsilon[g])^{\left(1-\chi_{s}\right) / 2} \varepsilon\left(I_{s}\right) \theta_{a_{s}}$, $s \in S, \varepsilon[g] \equiv \operatorname{sign} \operatorname{det}\left(g_{M N}\right)$.

The solutions presented above are valid if two restrictions on the sets of branes are satisfied, see [2].

For cylindrically symmetric case $M_{1}=S^{1}, g^{1}=d \phi \otimes d \phi, 0<\phi<2 \pi$, and $w=+1$ we get a family of composite fluxbrane solutions from [1].

## 2. POLYNOMIAL STRUCTURE OF $H_{s}$

In what follows we study the case $\varepsilon_{s}>0$ and $K_{s}>0$. In this case all $B_{s}>0$. Let us consider Eqs. (1) and (2) for the functions $H_{s}(z)>0, s \in S$. We are interested in analytical solutions of Eq. (1) in some disc $|z|<L$ :

$$
\begin{equation*}
H_{s}(z)=1+\sum_{k=1}^{\infty} P_{s}^{(k)} z^{k} \tag{11}
\end{equation*}
$$

where $P_{s}^{(k)}$ are constants, $s \in S$. The substitution of (11) into (1) gives an infinite chain of relations on parameters $P_{s}^{(k)}$ and $B_{s}$. The first relation in this chain

$$
\begin{equation*}
P_{s} \equiv P_{s}^{(1)}=\frac{1}{4} B_{s}=\frac{1}{4} K_{s} Q_{s}^{2}, \tag{12}
\end{equation*}
$$

$s \in S$, corresponds to $z^{0}$-term in the decomposition of (1).
It may be shown that for analytic functions $H_{s}(z), s \in S(11)\left(z=\rho^{2}\right)$ the metric (5) is regular at $\rho=0$ for $w=+1$, i.e., in the fluxbrane case.

It was conjectured in [1] that there exist polynomial solutions to Eqs. (1), (2)

$$
\begin{equation*}
H_{s}=1+\sum_{k=1}^{n_{s}} P_{s}^{(k)} z^{k} \tag{13}
\end{equation*}
$$

where $P_{s}^{(k)}$ are constants, $k=1, \ldots, n_{s}$. Here $P_{s}^{\left(n_{s}\right)} \neq 0$ and

$$
\begin{equation*}
n_{s}=2 \sum_{s^{\prime} \in S} A^{s s^{\prime}}, \quad s \in S \tag{14}
\end{equation*}
$$

Integers $n_{s}$ are components of the so-called twice dual Weyl vector in the basis of simple coroots. For the Lie algebra $A_{1}$ we get $H_{1}=1+P z$.

Special solutions. Let $P_{s}=n_{s} P, P>0, s \in S$. We get a special solution [1]

$$
\begin{equation*}
H_{s}=(1+P z)^{n_{s}}, \tag{15}
\end{equation*}
$$

$s \in S$, which is valid for any semisimple FD Lie algebra.

## 3. EXAMPLES

$F 6 \cap F 3$ fluxbrane solution related to Lie algebra $A_{2}$. Let $D=11$. $F 6 \cap F 3$ fluxbrane configuration with (nonstandard) $A_{2}$ intersection rules is defined on the manifold $M=(0,+\infty) \times M_{1} \times M_{2} \times M_{3} \times M_{4}$, where $d_{2}=2, d_{3}=5, d_{4}=2$.

The solution reads [1]

$$
\begin{gather*}
g=H_{e}^{1 / 3} H_{m}^{2 / 3}\left\{d \rho \otimes d \rho+H_{e}^{-1} H_{m}^{-1} \rho^{2} d \phi \otimes d \phi+H_{e}^{-1} g^{2}+H_{m}^{-1} g^{3}+g^{4}\right\}  \tag{16}\\
F=-Q_{e} H_{e}^{-2} H_{m} \rho d \rho \wedge d \phi \wedge \tau_{2}+Q_{m} \tau_{2} \wedge \tau_{4} \tag{17}
\end{gather*}
$$

where metrics $g^{2}$ and $g^{3}$ are (Ricci-flat) metrics of Euclidean signature, $g^{4}$ is the (flat) metric of the signature $(-,+)$ and

$$
\begin{equation*}
H_{s}=1+P_{s} \rho^{2}+\frac{1}{4} P_{1} P_{2} \rho^{4} \tag{18}
\end{equation*}
$$

where $P_{s}=(1 / 2) Q_{s}^{2}, s=e, m$.
$S 0$-brane solutions related to Lie algebras of rank 3 . Now we consider $S 0$-brane solutions defined on the manifold $M=\left(0, t_{0}\right) \times M_{1} \times M_{2}$, where $M_{1}$ is a one-dimensional manifold (say $S_{1}$ or $R$ ) and $M_{2}$ is a $(D-2)$-dimensional Ricci-flat manifold, $m=3$. Using (15) we get $H_{s}=X^{n_{s}}$, where $X=1+P t$, $P<0$. These solutions read

$$
\begin{gather*}
g=X^{2 A}\left\{-d t \otimes d t+X^{-2 B} t^{2} d \phi \otimes d \phi+g^{2}\right\}  \tag{19}\\
\exp \left(\varphi^{\alpha}\right)=X^{B_{1} \lambda_{1}^{\alpha}+B_{2} \lambda_{2}^{\alpha}+B_{3} \lambda_{3}^{\alpha}}  \tag{20}\\
F^{1}=-Q_{1} X^{n_{2}-2 n_{1}} t d t \wedge d \phi, \quad F^{2}=-Q_{2} X^{n_{1}-2 n_{2}+k_{1} n_{3}} t d t \wedge d \phi,  \tag{21}\\
F^{3}=-Q_{3} X^{k_{2} n_{2}-2 n_{3}} t d t \wedge d \phi \tag{22}
\end{gather*}
$$

where

$$
A=\frac{B}{D-2}, \quad B=\sum_{s=1}^{3} B_{s}, \quad B_{s}=n_{s} K_{s}^{-1}
$$

$k_{1}=(1,2,1), k_{2}=(1,1,2)$, for $A_{3}, B_{3}$ and $C_{3}$, respectively.
These solutions contain intervals with accelerated expansion of $M_{2}$-submanifold.

## CONCLUSIONS

Here we have done an overview of composite fluxbrane and $S$-brane solutions related to semisimple FD Lie algebras. The solutions were defined on a product of Ricci-flat manifolds $M_{i}$ which may have nonzero (chiral) parallel spinors. An open problem is to find the (fractional) numbers of unbroken supersymmetries for certain supergravitational solutions for various semisimple FD Lie algebras, e.g., to $A_{1} \oplus \ldots \oplus A_{1}$ (along a line as it was done in [4] for $M$-branes). Another problem is to find explicit formulae for fluxbrane polynomials related to all simple FD Lie algebras.

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